New Concepts of Dense set in i-Topological space and Proximity Space

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Article History:Received:11 January 2021; Accepted: 27 February 2021; Published online: 5 April 2021

Abstract: A new kind of some topological spaces concepts has been defined in i-topological spaces with respect to proximity spaces in our paper.

Keywords : i-topological spaces , \oint -dense , i-dense, $\mathcal{F}O$ dense, focal resolvable , ideal link	
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1. Introduction

In 1909 Riecs [10] introduce the concept of proximity relation then this concept was developed by Efremovic in 1952 [21] as this concept has been used on a large scale to produce a huge amount of different research in various disciplines like [3,4,8,11] After Kartowski's definition[9] of ideal in 1933 and his definition of ideal topological spaces which includes two structures, the ideal I and topological space (X,T), these concepts played a major role in the development of researches for a large number of researchers in various studies like [2,5,6]. A new topology for X has been constructed from the family T and the ideal I defined

by Irina [6] and its called the i-topological space which includes checked the following condition (1) \emptyset , $X \in T$, (2) for any $U \subseteq T$ there exist $U \in T$ such that $\bigcup U \approx U$ (3) for each $V, W \in T$ there exist $U \in T$ such that $V \cap W \approx U$ (4) $T \cap I = \{\emptyset\}$, Where \approx defined by $A \approx_B$ iff $A - B \cup B - A \in I$. Our work here includes studying the influences that can appear on some topological characteristics in i-topolgical space through their application using the proximity theory, and among these characteristics are: adherent point, density, resolvability as it was relying on some concepts that were presented in previous research [20]

2. PRELIMINARIES Definition (2-1) [20]: let (X, T, I) be a space then a subset, A of X is called focal set if there exist $U \in T(x)$, $x \in X$ such that $U\alpha A$, where $U\alpha A$ means that $U - A \in I$ and $I_{\oint}(x)$ denoted the set of all focal set of the point X. Definition (2-2)[20]:

Let (X,T,I) be a space and $A \subset X, x \subset X$, then x is named a \mathcal{F} -limit point of A iff for each $U \in I_{\oint}(x)$ such that $x \in U$ then $(Ux \cap A) - \{x\} \neq \emptyset$ and the set of all a limit point of A is named the focal derived set and denoted by $\mathcal{F}\mathbf{d}_{(A)}$, and $\mathcal{F}_{cl(A)=A \cup} \mathcal{F}\mathbf{d}_{A}$ and is named the focal closure of the set A

Definition (2-3) [20]:

let (X, T, I) is $\mathfrak{i}_{-\text{topology then}}$, The focal closure of a set A is denoted by $\mathcal{F}_{cl}(A)$ and defined by $\mathcal{F}_{cl}(A) = A \cup \mathcal{F}_{cl}(A)$ where $\mathcal{F}_{cl}(A)$ is the set of all focal limit points of the set A **Definition** (2-4) [20]:

 $_{let}(X, T, I)_{be \ a \ space \ and} A \subseteq X_{Then} i - cl(A)_{is \ the \ intersection \ of \ all}$

1- closed sets suppress of A. Definition (2-5): [20] let (X, T, I) be a space and (X, δ) is a proximity space and $B \subseteq X$ then a point $x \in X$ is called occlusion point of B if for each $U \in I_{\oint}(x), x \in U, U \delta B \oint (B)_{denoted the set}$ of all occlusion points of B. I. III - FOCAL ADHERENT POINT . Definition (3-1): let (X, T, I) is $i_{-Topological space and} (X, \delta)$ is a proximity space then a point $x \in X$ is called Focal adherent point of a subset A of X iff for each $U \in I_{\phi}(x)$, $U \cap A \neq \phi_{and is denoted by} \mathcal{F}_{adh}(A)$. now a relationship between $\mathcal{F}_{d}(A)$, $\mathcal{F}_{adh(A)}$, \oint (A), Fcl (A) as follows in the following proposition Proposition (3-2) : let (X, T, I) is i – Topological of space and (X, δ) is a proximity space and let A is a subset of X then each of the following $\mathcal{F}_{d}(A) \subseteq \mathcal{F}_{adb(A)} \subseteq \Phi_{(A)}$ 2. $\mathcal{F}_{adh(A)} \subseteq_{Fcl(A)}$ 3. If $A \in I_{\oint(\mathbf{x}), \text{ then }} \mathcal{F}_{adh(A)} = X$ 4. If $A \in I_{\text{then}} \mathcal{F}_{adh}(A) = \emptyset$ Proof (4) let $\mathbf{x} \in \mathbf{X}$ if possible that $\mathbf{x} \notin \mathcal{F}_{adh}(\mathbf{A})$, so there exist $\mathbf{U} \in \mathbf{I}_{\mathbf{A}}(\mathbf{x})$ such that $_{\rm U} \cap_{\rm A} = \emptyset$ but this mean that $\emptyset \in {}^{\rm I} _{\oint} (x)$ this contradiction. The following example shows that the convers is not true Let $X = {_{\{a,b,c\},T} = {_{\{X,\emptyset,\{a,c\}\}}, I = \{\emptyset, \{c\}\}} and A = \{a,c\}_{then}$ $\mathcal{F}_{adh} \{a, c\} = X_{but} A \notin I_{\phi} (b) \text{ and for } B = \{b\}_{Then} \mathcal{F}_{adh \{b\}} = \phi_{but \{b\}} \notin I_{Adh \{b\}}$ **Definition** (4-1) : let (X, T, I) is $i_{-\text{Topological space and }} (X, \delta)$ is a proximity space and $A \subseteq X$ Then A is called 1) $\mathbf{i}_{-\text{dense iff}} \mathbf{i}_{-\text{cl}(A)} = \mathbf{x}$ 2) Focal dense iff $\mathcal{F}_{cl(A)} = {}_{X \text{ and is denoted by}} \mathcal{F}_{0}_{dense}$ 3) $\oint_{\text{-dense iff}} \oint_{(A)} =_{X}$ we obtain a relationship that connect both \mathcal{FO}_{dense} , \oint -dense and i-dense as in the following **Proposition** (4-2): Let (X, T, I) is $i_{-Topological space and} (X, \delta)$ is approximity space then 1. Every $\mathcal{F}O_{\text{dense set is}} \oint_{-\text{dense}}$

2. Every $\mathcal{F}_{\text{dense set is}}^{i}$ i – dense set The following example shows that the converse of above Proposition is not true Example : (4-3) $X = \{a,b,c\}, T = \{\{X, \emptyset, \{a, b\}, \{a, c\}\}, I = \{\emptyset, \{c\}\}, and A = \{b,c\}, then A is I - dense But not \}$ $\mathcal{FO}_{\text{dense}}$ **Proposition** (4-4): Let (X, T, I) is $i_{-\text{Topological space and }}(X, \delta)$ is a proximity space and $A, B \subseteq X$ then the following are holds: 1. $A \subseteq B$ such that A is $\mathcal{F}O_{\text{dense then } B \text{ is }} \mathcal{F}O_{\text{dense}}$ 2. If $A \cap B$ is $\mathcal{F}O_{\text{dense then } A, B}$ are $\mathcal{F}O_{\text{dense}}$ 3. A, B are $\mathcal{FO}_{\text{dense then A}} \cup B_{\text{is}} \mathcal{FO}_{\text{dense}}$ Proof: (1) Let $A \subseteq B$ such that A is $\mathcal{F}\mathbf{0}_{dense then} \mathcal{F}_{cl(A)} = X$, hence $\mathcal{F}_{cl(B)} = X$ so B is $\mathcal{F}\mathbf{0}_{dense}$ **Example (4-5) :** $X = \{a, b, c\}, T = \{X, \emptyset, \{a\}\}, I = \{\emptyset\}_A = \{b\}_{and B} = \{a, b\}_{clearly that A} \subseteq_B and \mathcal{F}_{cl(B)} = X$ But $\mathcal{F}_{cl\{b\}} \neq X$ Example : (4-6) $X = \{a, b, c\}, T = \{X, \emptyset, \{a, b\}\}_{and} I = \{\emptyset\}_{then A} = \{a, c\}, B = \{b, c\}_{are} \mathcal{F}O_{dense but, A} \cap_{B} \in A} \cap_{B} \cap_$ {c} is not $\mathcal{F}O_{\text{dense. Also }H} = {b}, K = {c}, H \cup K is \mathcal{F}O_{\text{dense but }B is not} \mathcal{F}O_{\text{dense but }B is not}$ **Remark : (4-7)** for each A in I, A is not \mathcal{FO}_{dense} **Proposition : (4-8)** Let (X, T, I) is $i_{\text{Topological space and }}(X, \delta)$ is a proximity space, the following properties are holds: 1. A is $i_{\text{-dense iff}} U \cap A \neq \emptyset_{\text{for each } U} \in_{T}$ 2. A is $\mathcal{F}O_{\text{dense then}} U \cap A \neq \emptyset_{\text{for each U}} \in T$ Proof (1) if possible that $U \cap_A = \emptyset$ then there exist $U \in_{T_{(x)}} U \cap A = \emptyset$, so $x \notin i_{-cl}(A)$ and this is contradiction hence $\mathbf{U} \cap \mathbf{A} \neq \emptyset$, for each $\mathbf{U} \in \mathbf{U}$. Conversely, since $\mathbf{U} \cap \mathbf{A} \neq \emptyset$ for each, $\mathbf{U} \in \mathbf{U}$, and for each x in X, so $\mathbf{i}_{-cl}(\mathbf{A})$ $=_{X, hence, A is} i_{-dense set}$ (2) the proof is similar to (1)Example : (4-9) $_{X} = {}_{\{a,b,c\}, T} = {}_{\{X, \emptyset, \{a,b\}, \{a,c\}\} \text{ and }} I = {}_{\{\emptyset, \{c\}\} \text{ for a proximity space}} \delta_{\text{ defined by } A} \delta B_{\text{ iff }} B \cap A \neq \emptyset$ if we take $A = {b,c}$ is not $\mathcal{F}O_{dense we get that U} \cap A \neq_{\emptyset \text{ for each }} U \in \mathbf{T}$. **Example : (4-10)** $X = \{a, b, c\}, I = \{\emptyset, \{a\}\}$ and $T = \{X, \emptyset\}$ for a proximity space δ defined by ${}_{A} \delta B \text{ iff } B \cap A \neq \emptyset \quad \text{clearly that } A = {}_{\{a\} \text{ is not}} \oint dense \text{ set but}, U \cap A \neq \emptyset, \forall U \in T$

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Proposition: (4-11)

Let (X,T, \mathbf{I}_{i} is $\mathbf{i}_{\text{-Topological space and}} (\mathbf{X}, \boldsymbol{\delta})$ is a proximity space, A is $\mathcal{F}\mathbf{O}_{\text{dense iff}} \mathcal{F}_{\text{adh}(A)} = X$ **Proof** : Let A is \mathcal{F}_{0} dense if possible that $\mathcal{F}_{adh(A)} \neq X$ so there exist $\mathbf{x} \in X$ such that $\mathbf{x} \notin \mathcal{F}_{adh(A)}$, and by (3-2)(1), $\mathbf{x} \notin \mathcal{F}_{adh(A)}$ $\mathcal{F}_{d(A) \text{ that we get there exist } U} \in I_{\oint}(\boldsymbol{x})_{, x} \in U_{, U} \cap_{A} = \mathcal{I}_{\emptyset} \text{ and then } x \notin A, \text{ from that we get } \boldsymbol{x} \notin \mathcal{F}_{cl(A) \text{ and } from that } \boldsymbol{x} \notin \mathcal{F}_{cl(A)}$ this is contradiction by assume , hence $\mathcal{F}_{-adh (A)} = {}_{X, Conversely, let} \mathcal{F}_{adh (A)} = {}_{X and by proposition (3-2) we get that}$ $_{A is} \mathcal{F}O_{dense}$ **Proposition** (4-12) : Let (X,T, I) is $i_{\text{-Topological space and}} (X, \delta)$ is a proximity space, if A is $\mathcal{F}O_{\text{dense then}} \mathcal{F}_{adh(A)} = \mathcal{F}_{cl(A)}$. Example :(4-13) Let $X = {a,b,c}, T = {X, \emptyset, {a}}$ and $I = {\emptyset, {c}}$ when $A = {b}$ then clearly that $\mathcal{F}_{cl(A)} = \mathcal{F}_{adh(A)}$ But A is not \mathcal{FO}_{dense} **Definition : (4-14)** Let (X,T, I) is **i**-Topological space and (X, δ) is a proximity space then X is called : 1. $\mathbf{i}_{\text{-resolvable if there exist } A,B} \subseteq \mathbf{x}_{A,B} \neq \emptyset$ are disjoint $\mathbf{i}_{\text{-dense sets such that } A} \cup_{B} = \mathbf{x}_{A,B}$ 2. Focal resolvable if there exist non empty disjoint $\mathcal{FO}_{dense sets A, B such that X} = {}_{A} \cup {}_{B}$ 3. \oint resolvable if there exist non empty \oint dense sets A, B such that $A \overline{\delta} B and A \delta B^{c}$ 1. Proposition (4-15) : Let (X,T, I) is i-Topological space and (X, δ) is a proximity space if X is Focal resolvable then X is i-resolvable. **Proof**: By proposition (4-2)(1) the result exist Example (4-16) : Let X = {a,b,c}, T = {X,Ø,{a,b},{a,c}} I = {Ø,{c},{b},{b,c}}, then X is $\mathbf{i}_{-\text{resolvable But not Focal resolvable}}$ V - IDEAL LINK **Definition (5-1) :** Let (X,T_1, I) and (X,T_2, I) are i-Topological spaces then we say that T_1 ideal link to T_2 if for each U is proper subset of X in T₁ there exist a proper subset of X, V in T₂ Such that $U\alpha V$ If T₁ is ideal link to T₂ we denoted that by T₁ Δ T₂ **Example (5-2):** Let X = {a,b,c}, T₁ = {X, Ø,{a}} and T₂ = {X, Ø,{a},{b}} if I = {Ø,{c}} That $T_1 \Sigma T_2$ But T_2 is not ideal link to T_1 **Proposition (5-3):** Let $(X,T_i, I_i, j = 1,2$ are i – topological spaces If $T_1 \subseteq T_2$ then $T_1 \land T_2$ proof: let $U \in T_1$ then there exist $V = U \in T_2$ such that $U \alpha_{V \text{ so } T_1} \alpha_{T_2}$ The converse of the above Proposition is not true as in the fallowing example Example (5-4): Let X={a,b,c}, T₁ = {X, Ø,{a}}, I = {Ø,{c}}, T₂ = {X, Ø,{a,b}}, Then T₁X T₂ But T₁ $\not\subseteq$ T₂ **Proposition** (5-5):

Let (X,T_i, I_i) , j = 1,2 are i – topological spaces and $I \neq \{\emptyset\}$ If $T_1 \subseteq T_2$ then $I_{\phi_{T_1(x)}} \subseteq I_{\phi_{T_2(x)}}$ Remark (5-6) : (X, T_{ind}, I) when I is ang ideal on X is ideal link to any i-Topological space on X **Proposition (5-7)**: Let (X, T_i, \mathbf{I}), $\mathbf{j} = 1,2$ are $\mathbf{i}_{-\text{Topological spaces then } T_1 X T_2}$ iff for each $A \in T_1$ there exist $B \in T_2$, $A \subseteq B$ Proof · Let $A \in_{T_1}$ and $X \in_A$ hence there exist $B \in_{T_2}$ such that $A \alpha_B$ that is $A \cap_{B^c} \in I_{\text{now If possible that }} x \notin_{B, \text{ then }}, x \in_{B^c \text{ that is } \{x\}} \in I_{\text{, for each }} x \in_{A, \text{ so we get that }} A \in I_{\text{ which is }}$ contradiction and therefore $A \subseteq B$. Conversely, let A \in_{T_1} so there exist, $B \in_{T_2}$ and $A \subseteq_B$ which meaning that $A \cap_{B^c} = \emptyset$ imply $A \alpha_B$ Then $T_1 \Delta$ **Proposition (5-9):** Let (X,T_i, I) i = 1,2 are $i_{-Topological space and} (X, \delta)$ such that $I \neq \{\emptyset\}$ and $T_1 \subseteq T_2$ Then $\mathcal{F}d_{\mathbf{T}_{2}(A)} \subseteq \mathcal{F}d_{\mathbf{T}_{1}(A)}$ $\mathcal{F}adh_{T_{2(A)}} \subseteq \mathcal{F}adh_{T_{1(A)}}$ (4) Every $\mathcal{F}\mathbf{0}_{dense}$ with respect to T_2 is $\mathcal{F}\mathbf{0}_{dense}$ with respect to T_1 (5) If X is focal resolvable with respect to T_2 then X is focal resolvable with respect to T_1 Proof:(4) let A is $\mathcal{F}O_{\text{dense with respect to }T_2 \text{ and by }(2) \text{ A is } \mathcal{F}O_{\text{dense with respect to }T_1}$ Example: (5-9) $\sum_{L \in X} = \{a, b, c\}, T_1 = \{X, \emptyset, \{a\}\}, T_2 = \{X, \emptyset, \{a\}, \{c\}\} \text{ and } I = \{\emptyset, \{b\}\}, if A =_{\{a\} \text{ then } A \text{ is} }$ $\mathcal{FO}_{T_1-\text{ dense But not}} \mathcal{FO}_{T_2 \text{ dense}}$ Example: (5-10) ${X, \emptyset, {a, b}}$ = = $\{a,b,c\}$ T_1 Let Х $T_2 =$ $\{X, \emptyset, \{a\}, \{b\}, \{b, a\}\}$ and I = $\{\emptyset, \{b\}\}$, then X is T₁- Focal resolvable But not T₂ – Focal resolvable CONCLUSION : 1. the definition of density in i – topological spaces with respect to proximity space showed some effects through the application

in some theories and properties that have been studied as well as some concepts such as . 2. the concept of ideal link between two i – topological spaces presented in this paper is another from of the concept of coarser and finer in the previously defined topological spaces

3. Within the environment in which you work, we can apply the previous definitions in a set of concepts used by some researchers, such as the concept of w-open[17,18,19] and Para compactness [15,16], as well as the concept of soft set [1,12,13] and the concept of gem set [14].

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