Some Fixed Point Theorems For Mappings Satisfying Contractive Conditions Of Integral Type

Naveen Jha

Department of Mathematics, Government Engineering College, Bharatpur, Rajasthan, India-321001, E-mail; naveenjha2410@gmail.com

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Abstract: In this paper, we establish some common fixed-point theorems for two pairs of weakly compatible mappings satisfying integral type contractive conditions integral type in dislocated metric spaces by using E.A. which improves and extends similar known results in the literature.

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1.Introduction

In 1922, S. Banach proved a fixed point theorem for contraction mapping in metric space. Since then a number of fixed point theorems have been proved by different authors, and many generalizations of this theorem have been established. Jungck [7] generalized the Banach contraction principle by introducing a contractive condition for a pair of commuting self-mappings on metric space and pointed out the potential of commuting mappings for generalizing fixed point theorems in metric spaces. Jungck's [7] results have been further generalized.

Sessa [24], initiated the tradition of improving commutativity conditions in metrical common fixed point theorems. While doing so Sessa [24] introduced the notion of weak commutativity. Motivated by Sessa [24], Jungck [8] defined the concept of compatibility of two mappings, which includes weakly commuting mappings as a proper subclass. Jungck and Rhoades [10] introduced the notion of weakly compatible (coincidentally commuting) mappings and showed that compatible mappings are weakly compatible but not conversely. Many interesting fixed point theorems for weakly compatible maps satisfying contractive type conditions have been obtained by various authors. The concept of compatible mappings was frequently used to show the existence of common fixed points. However, the study of the existence of common fixed points for noncompatible mappings is also very interesting. Aamri and Moutawakil [4] gave a notion (E.A) which generalizes the concept of noncompatible mappings in metric spaces.

Branciari [2] introduced the notion of contraction of integral type and proved first fixed point theorem for this class of mapping. Further results on this class of mappings were obtained by Rhoades [22], Aliouche [3], Djoudi and Merghadi [6] and many others.

. Matthews [11] introduced some concepts of metric domains in the context of domain theory The notion of a dislocated metric (*d-metric*) space was introduced by Pascal Hitzler in [12] as a part of the study of logic programming semantics. The study of common fixed point mappings in dislocated metric space satisfying certain contractive conditions has been at the center of vigorous research activity, see for example in [13-21].

In this article, we have established some common fixed point results of integral type contractive conditions using the concept of weakly compatible mappings with (E. A.) property in dislocated metric (*d-metric*) space. Our obtained results generalizes some well known results of the literature.

2. Preliminary Notes

We begin by recalling some basic concepts of the theory of dislocated metric (*d-metric*) spaces.

Definition 2.1 Let X be a non empty set and let $d: X \times X \to [0, \infty)$ be a function satisfying the following conditions:

(i)
$$d(x, y) = d(y, x)$$

- (ii) d(x, y) = d(y, x) = 0 implies x = y
- (iii) $d(x, y) \le d(x, z) + d(z, y)$ for all $x, y, z \in X$

Then d is called dislocated metric (or simply *d*-metric) on X.

Definition 2.2 A sequence $\{x_n\}$ in a *d*-metric space (X, d) is called a Cauchy sequence if for given $\epsilon > 0$, there exists $n_0 \in N$ such that for all $m, n \ge n_0$, we have $d(x_m, x_n) < \epsilon$.

Definition 2.3 A sequence in *d*-metric space converges if there exists $x \in X$ such that $d(x_n, x) \to 0$ as $n \to \infty$.

Definition 2.4 A d-metric space (X, d) is called complete if every Cauchy sequence is convergent.

Definition 2.5 Let (X, d) be a d-metric space. A map $T: X \to X$ is called contraction if there exists a number λ with $0 \le \lambda < 1$ such that $d(Tx, Ty) \le \lambda d(x, y)$.

Definition 2.6 Let A and S be two self mappings on a set X. Mappings A and S are said to be commuting if $ASx = SAx \quad \forall x \in X$.

Definition 2.7. Let S and T be mappings of a metric space (X, d) into itself. Then (S, T) is said to be weakly commuting pair if

 $d(STx, TSx) \le d(Tx, Sx)$ for all $x \in X$.

Obviously a commuting pair is weakly commuting but its converse need not be true as is evident from the following example.

Example 2.1. Consider the set X = [0, 1] with the usual metric. Let $Sx = \frac{x}{2}$ and $Tx = \frac{x}{2+x}$ for every $x \in X$. Then for all $x \in X$

$$STx = \frac{x}{4+2x}, TSx = \frac{x}{4+x}.$$

Hence $ST \neq TS$. Thus S and T do not commute.

Again

$$d(STx, TSx) = \left|\frac{x}{4+2x} - \frac{x}{4+x}\right| = \frac{x^2}{(4+x)(4+2x)}$$
$$\leq \frac{x^2}{(4+2x)} = \frac{x}{2} - \frac{x}{2+x} = d(Sx, Tx),$$

and so, S and T commute weakly.

Obviously, the class of weakly commuting is wider and includes commuting mappings as subclass.

Definition 2.8. Two self mappings S and T from a *d*-metric space (X, d) into itself are called compatible if and only if

 $\lim_{n \to \infty} d(STx_n, TSx_n) = 0$, whenever $\{x_n\}$ is a sequence in X such that

$$\lim_{n \to \infty} Sx_n = \lim_{n \to \infty} Tx_n = t \text{ for some } t \in X.$$

Very recently concept of **weakly compatible** obtained by Jungck-Rhoades [10] stated as the pair of mappings is said to be weakly compatible if they commute at their coincidence point.

Example 2.2.

Let X = [0, 3] be equipped with the usual *d*-metric space d(x, y) = |x - y|.

Define S, T: [0, 3] \rightarrow [0, 3] by Sx = $\begin{cases} x, x \in [0,1) \\ 3, x \in [1,3] \end{cases}$ and Tx = $\begin{cases} 3-x, x \in [0,1) \\ 3, x \in [1,3] \end{cases}$

Then for any $x \in [1, 3]$, STx = TSx, showing that S and T are weakly compatible maps on [0, 3].

Definition 2.9: Let S and T be two self mappings of a *d*-metric space (X, d). We say that S and T satisfy the property (E.A) if there exist a sequence $\{x_n\}$ such that

 $\lim_{n \to \infty} Sx_n = \lim_{n \to \infty} Tx_n = u$, for some $u \in X$.

Proposition 2.1 Let S and T be compatible mappings from a d-metric space (X, d) into itself. Suppose that

 $\lim_{n \to \infty} Sx_n = \lim_{n \to \infty} Tx_n = x \text{ for some } x \in X.$

if S is continuous then $\lim_{n \to \infty} TSx_n = Sx$.

Theorem 2.1 Let (X, d) be a complete d-metric space and let $T: X \to X$ be a contraction mapping, then T has a unique fixed point.

3. Main Results

Now, we establish a common fixed point theorem for two pairs of weakly compatible mappings using E. A. property. **Theorem 3.1** Let (X, d) be a complete dislocated metric space. Let $A, B, S, T, I, J: X \to X$ satisfying the following conditions

(i)
$$AB(X) \subseteq J(X)$$
 and $ST(X) \subseteq I(X)$...(1)

(ii)
$$\int_0^{d(ABX,STy)} \phi(t) dt \le k \int_0^{M(x,y)} \phi(t) dt, k \in \left[0, \frac{1}{9}\right]$$
... (2)

for all $(x, y) \in X \times X$ where $\emptyset: \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesgue integrable mapping which is summable, non-negative and such that

$$\int_0^{\infty} \phi(t) dt > 0 \text{ for all } \epsilon > 0. \qquad \dots (3)$$

$$M(x,y) = d(Ix,Jy) + d(Ix,ABx) + d(Jy,STy) + d(Ix,STy) + d(Jy,ABx)$$
(4)

- (iii) The pairs (AB, I) or (ST, I) satisfy E.A. property.
- (iv) The pairs (AB, I) and (ST, I) are weakly compatible.

If I(X) is closed then the mappings AB,ST,I and J have a unique common fixed point in X. Furthermore, if the pairs (A,B), (A,I), (B,I), (S,T), (S,J) and (T,J) are commuting mappings then A, B, S, T, I and J have a unique common fixed point in X.

Proof:

Assume that the pair (AB, I) satisfy E. A. property, so there exists a sequence $\{x_n\} \in X$ Such that $\lim_{n \to \infty} ABx_n = \lim_{n \to \infty} Ix_n = u$...(5)

For some $u \in X$. Since $AB(X) \subseteq J(X)$, so there exists a sequence $\{y_n\} \in X$ such that $ABx_n = Jy_n$. Hence, $\lim_{n \to \infty} ABx_n = \lim_{n \to \infty} Jy_n = u$...(6)

From condition (2), we have

$$\int_0^{d(ABx_n,STy_n)} \phi(t)dt \le k \int_0^{M(x_n,y_n)} \phi(t)dt, \qquad \dots (7)$$

where

$$M(x_n, y_n) = d(Ix_n, Jy_n) + d(Ix_n, ABx_n) + d(Jy_n, STy_n) + d(Ix_n, STy_n) + d(Jy_n, ABx_n)$$

Taking limit as $n \to \infty$, we get

$$\lim_{n \to \infty} \int_0^{d(ABx_n, STy_n)} \phi(t) dt \le k \lim_{n \to \infty} \int_0^{M(x_n, y_n)} \phi(t) dt \qquad \dots (8)$$

Since

$$\lim_{n \to \infty} d(Ix_n, Jy_n) = \lim_{n \to \infty} d(Ix_n, ABx_n) = \lim_{n \to \infty} d(Jy_n, ABx_n) = 0$$
$$\lim_{n \to \infty} d(STy_n, Jy_n) = \lim_{n \to \infty} d(Ix_n, STy_n) = \lim_{n \to \infty} d(STy_n, u)$$

Therefore, we have

$$\lim_{n \to \infty} \int_0^{d(u, STy_n)} \phi(t) dt \le 2k \lim_{n \to \infty} \int_0^{d(u, STy_n)} \phi(t) dt$$

which is a contradiction, since $k \in [0, \frac{1}{g}]$. Hence $\lim_{n \to \infty} STy_n = u$. Since $ST(X) \subseteq I(X)$, so there exists a sequence $x_n \in X$ such that $STx_n = Ix_n$. Hence, we have

$$\lim_{n \to \infty} ABx_n = \lim_{n \to \infty} Jy_n = \lim_{n \to \infty} STy_n = \lim_{n \to \infty} Ix_n = u$$

Assume I(X) is closed, then there exists $v \in X$ such that Iv = u. We claim that ABv = u. Now from condition (2),

$$\int_0^{d(ABv,STy_n)} \phi(t) dt \le k \int_0^{M(v,y_n)} \phi(t) dt,$$

where

$$M(v, y_n) = d(J y_n, ABv) + d(Iv, Jy_n) + d(Iv, ABv) + d(ST y_n, Jy_n) + d(Iv, ST y_n) ...(9)$$

Since $\lim_{n \to \infty} d(Jy_n, ABv) = d(u, ABv)$

$$\lim_{n \to \infty} d(Iv, Jy_n) = \lim_{n \to \infty} d(STy_n, Jy_n) = \lim_{n \to \infty} d(Iv, STy_n) = 0$$

So, taking limit as $n \to \infty$ in (9), we conclude that

$$\int_0^{d(ABv,u)} \phi(t) dt \le 2k \int_0^{d(u,ABv)} \phi(t) dt \qquad \dots (10)$$

which is a contradiction, since $k \in \left[0, \frac{1}{g}\right)$. Hence, $d(ABv, u) = 0 \Rightarrow ABv = u$.

Now, we have

$$ABv = u = Iv \qquad \dots(11)$$

This proves that v is the coincidence point of (AB, I).

Again $AB(X) \subseteq J(X)$ so there exists $w \in X$ such that

$$ABv = Jw = u$$

Now, we claim that STw = u. From condition (2), we have

$$\begin{split} \int_{0}^{d(u,STW)} \phi(t) dt &= \int_{0}^{d(ABV,STW)} \phi(t) dt \leq k \int_{0}^{M(v,w)} \phi(t) dt, \text{ where} \\ M(v,w) &= d(Iv,Jw) + d(Iv,ABv) + d(Jw,STw), d(Iv,STw) + d(Jw,ABv) \\ &= d(u,u) + d(u,u) + d(u,STw) + d(u,STw) + d(u,u) \\ &= 3d(u,u) + 2d(u,STw) \\ &\leq 3\{d(u,STw) + d(STw,u)\} + 2d(u,STw) \\ &\leq 8d(u,STw) \\ & \text{Hence,} \int_{0}^{d(u,STW)} \phi(t) dt \leq 8k \int_{0}^{d(u,STW)} \phi(t) dt, \end{split}$$

which is a contradiction, since $k \in \left[0, \frac{1}{2}\right)$.

Hence, $d(u, STw) = 0 \Rightarrow STw = u$.

Therefore, STw = u = Jw.

This represents that w is the coincidence point of the maps ST and J. Hence,

u = STw = Jw = Iv = ABv

Since the pair (ST, J) and (AB, I) are weakly compatible so,

STJw = JSTw, IABv = ABIvSince Iu = IABv = ABIv = ABu and Ju = JSTw = STJw = STu, we claim that STu = u. From condition (2), we have

$$\begin{split} \int_{0}^{d(u,STu)} & \phi(t) \, dt = \int_{0}^{d(ABv,STu)} \phi(t) \, dt \leq k \int_{0}^{M(v,u)} \phi(t) \, dt, \, \text{where} \\ & M(v,u) = d(Iv,Ju) + d(Iv,ABv) + d(Ju,STu) + d(Iv,STu) + d(Ju,ABv) \\ & = d(u,STu) + d(u,u) + d(STu,STu) + d(u,STu) + d(STu,u) \\ & = 3d(u,STu) + d(u,u) + d(STu,STu) \\ & \leq 7d(u,STu) \\ & \text{Hence,} \int_{0}^{d(u,STu)} \phi(t) \, dt \leq 7k \int_{0}^{d(u,STu)} \phi(t) \, dt, \end{split}$$

which is a contradiction, since $k \in \left[0, \frac{1}{o}\right)$.

Hence, $d(u, STu) = 0 \Rightarrow STu = u$. Therefore, u = STu = Ju. Similarly, ABu = u = Iu. Hence, u = ABu = STu = Iu = Ju. This represents that u is a common fixed point of the mappings AB, ST, I and J. Uniqueness: If possible, let $z(\neq u)$ be other common fixed point of the mappings, then by the condition (2) $\int_{0}^{d(u,z)} \phi(t) dt = \int_{0}^{d(ABu,STz)} \phi(t) dt \le k \int_{0}^{M(u,z)} \phi(t) dt$, where

$$\begin{split} M(u,z) &= d(Iu,Jz) + d(Iu,ABu) + d(Jz,STz) + d(Iu,STz) + d(Jz,ABu) \\ &= d(u,z) + d(u,u) + d(z,z) + d(u,z) + d(z,u) \\ &= 3d(u,z) + d(u,u) + d(z,z) \\ &\leq 7d(u,z) \\ \end{split}$$
Hence, $\int_0^{d(u,z)} \phi(t) \, dt \leq 7k \int_0^{d(u,z)} \phi(t) \, dt,$

which is a contradiction, since $k \in [0, \frac{1}{6}]$.

Hence, $d(u, z) = 0 \Rightarrow u = z$. This establishes the uniqueness of the common fixed point of mappings *AB*, *ST*, *I* and *J*. Finally, we prove that *u* is also a common fixed point of A, B, S, T, I and J. Let both the pairs (*AB*, *I*) and (*ST*, *J*) have a unique common fixed point *u*.

Then.

 $\begin{aligned} Au &= A(ABu) = A(BAu) = AB(Au) \\ Az &= A(Iu) = I(Au) \\ Bu &= B(ABu) = B(A(Bu)) = BA(Bu) = AB(Bu) \\ Bu &= B(Iu) = I(Bu) \end{aligned}$

which implies that (AB, I) has common fixed points which are Au and Bu. We get thereby Au = u = Bu = Iu = ABu.

Similarly, using the commutativity of (S, T), (S, J) and (T, J), Su = u = Tu = Ju = STu can be shown. Now, we need to show that Au = Su (Bu = Tu).

By using condition (2), we have

$$\int_{0}^{d(Au,Su)} \varphi(t) dt = \int_{0}^{d(A(ABu),S(STu))} \varphi(t) dt = \int_{0}^{d(A(BAu),S(TSu))} \varphi(t) dt$$
$$= \int_{0}^{d(AB(Au),ST(Su))} \varphi(t) dt$$
$$\leq \int_{0}^{M(Au,Su)} \varphi(t) dt$$

where,

$$\begin{split} M(Au, Su) &= d(I(Au), J(Su)) + d(I(Au), AB(Au)) + d(J(Su), ST(Su)) + d(I(Au), ST(Su)) + d(J(Su), AB(Au)) \\ &= d(Au, Su) + d(Au, Au) + d(Su, Su) + d(Au, Su) + d(Su, Au) \\ &\leq 3d(Au, Su) + d(Au, Au) + d(Su, Su) \\ &\leq 7d(Au, Su) \end{split}$$

Therefore, $\int_0^{d(Au,Su)} \varphi(t) dt \le 7k \int_0^{d(Au,Su)} \varphi(t) dt$, which is a contradiction, since $k \in \left[0, \frac{1}{g}\right]$. Hence,

 $\int_{0}^{d(Au,Su)} \varphi(t) dt = 0$ $\Rightarrow d(Au, Su) = 0$ $\Rightarrow Au = Su.$

Similarly, Bu = Tu can be shown.

Consequently, z is a unique common fixed point of A, B, S, T, I and J.

If we put AB = A, ST = B in Theorem (3.1), we get the following, which generalize the result of Panthi and Subedi [20] in dislocated metric spaces.

Corollary 3.1. Let (X, d) be a complete dislocated metric space. Let $A, B, I, J: X \to X$ satisfying the following conditions

(i) $A(X) \subseteq J(X)$ and $B(X) \subseteq I(X)$

(ii) $\int_0^{d(Ax,By)} \phi(t) dt \le k \int_0^{M(x,y)} \phi(t) dt, k \in \left[0, \frac{1}{9}\right]$

for all $(x, y) \in X \times X$ where $\emptyset: \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesgue integrable mapping which is summable, non-negative and such that

 $\int_0^{\epsilon} \phi(t) dt > 0 \text{ for all } \epsilon > 0.$

M(x, y) = d(Ix, Jy) + d(Ix, Ax) + d(Jy, By) + d(Ix, By) + d(Jy, Ax)

(iii) The pairs (A, I) or (B, J) satisfy E.A. property.

(iv) The pairs (A, I) and (B, J) are weakly compatible.

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If I(X) is closed then the mappings A,B,I and J have a unique common fixed point in X.

If we put A=B in the above Corollary 3.1, we can obtain the following corollary easily.

Corollary 3.2. Let (X, d) be a complete dislocated metric space. Let $A, I, J: X \to X$ satisfying the following conditions

(i) $A(X) \subseteq J(X)$ and $A(X) \subseteq I(X)$

(ii) $\int_{0}^{d(Ax,Ay)} \phi(t) dt \leq k \int_{0}^{M(x,y)} \phi(t) dt, k \in \left[0, \frac{1}{9}\right]$

for all $(x, y) \in X \times X$ where $\emptyset: \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesgue integrable mapping which is summable, non-negative and such that

 $\int_{0}^{e} \phi(t) dt > 0 \text{ for all } \epsilon > 0.$ M(x, y) = d(Ix, Jy) + d(Ix, Ax) + d(Jy, Ay) + d(Ix, Ay) + d(Jy, Ax)

(iii) The pairs (A, I) or (A, J) satisfy E.A. property.

(iv) The pairs (A, I) and (A, J) are weakly compatible.

If I(X) is closed then the mappings A,I and J have a unique common fixed point in X.

If we put I=J in the above Corollary 3.1, we can obtain the following corollaries easily.

Corollary 3.3. Let (X, d) be a complete dislocated metric space. Let $A, B, I: X \to X$ satisfying the following conditions

(i) $A(X) \subseteq I(X)$ and $B(X) \subseteq I(X)$

(ii)
$$\int_{0}^{d(Ax,By)} \phi(t)dt \leq k \int_{0}^{M(x,y)} \phi(t)dt, k \in \left[0, \frac{1}{9}\right]$$

for all $(x, y) \in X \times X$ where $\emptyset: \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesgue integrable mapping which is summable, non-negative and such that

 $\int_0^{\epsilon} \phi(t) \, dt > 0 \text{ for all } \epsilon > 0.$

M(x, y) = d(Ix, Iy) + d(Ix, Ax) + d(Iy, By) + d(Ix, By) + d(Iy, Ax)

(iii) The pairs (A, I) or (B, I) satisfy E.A. property.

(iv) The pairs (A, I) and (B, I) are weakly compatible.

If I(X) is closed then the mappings A,B and I have a unique common fixed point in X.

If we put A=B and I=J in the above Corollary 3.1, we can obtain the following corollaries easily.

Corollary 3.4. Let (X, d) be a complete dislocated metric space. Let $A, I: X \to X$ satisfying the following conditions

(i)
$$A(X) \subseteq I(X)$$

(ii)
$$\int_{0}^{d(Ax,Ay)} \phi(t) dt \leq k \int_{0}^{M(x,y)} \phi(t) dt, k \in \left[0, \frac{1}{g}\right]$$

for all $(x, y) \in X \times X$ where $\emptyset: \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesgue integrable mapping which is summable, non-negative and such that

 $\int_0^{\epsilon} \phi(t) dt > 0 \text{ for all } \epsilon > 0.$ M(x, y) = d(Ix, Iy) + d(Ix, Ax) + d(Iy, Ay) + d(Ix, Ay) + d(Iy, Ax)

(iii) The pairs (A, I) satisfy E.A. property.

(iv) The pairs (A, I) are weakly compatible.

If I(X) is closed then the mappings A and I have a unique common fixed point in X.

Now, we establish the following theorem for six mappings involving Ciric's[5] type contractive condition in complete dislocated metric spaces.

Theorem 3.2 Let (X,d) be a complete dislocated metric space. Let $A, B, S, T, I, J: X \to X$ satisfying the following conditions

(i) $AB(X) \subseteq J(X)$ and $ST(X) \subseteq I(X)$...(12)

(ii)
$$\int_{0}^{d(ABx,STy)} \phi(t) dt \le k \int_{0}^{M(x,y)} \phi(t) dt, k \in [0, \frac{1}{2}]$$
 ... (13)

for all $(x, y) \in X \times X$ where $\emptyset: \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesgue integrable mapping which is summable, non-negative and such that

 $\int_{0}^{\epsilon} \phi(t) dt > 0 \text{ for all } \epsilon > 0. \qquad \dots (14)$ $M(x,y) = \max\{d(Ix,Jy), d(Ix,ABx), d(Jy,STy), d(Ix,STy), d(Jy,ABx)\}, \qquad \dots (15)$

(iii) The pairs (AB, I) or (ST, J) satisfy E.A. property.

(iv) The pairs (AB, I) and (ST, J) are weakly compatible.

If I(X) is closed then the mappings AB,ST,I and J have a unique common fixed point in X. Furthermore, if the pairs (A,B), (A,I), (B,I), (S,T), (S,J) and (T,J) are commuting mappings then A, B, S, T, I and J have a unique common fixed point in X.

Proof:

Assume that the pair
$$(AB, I)$$
 satisfy E. A. property, so there exists a sequence $\{x_n\} \in X$ Such that

$$\lim_{n \to \infty} ABx_n = \lim_{n \to \infty} Ix_n = u \qquad \dots (16)$$

For some $u \in X$. Since $AB(X) \subseteq J(X)$, so there exists a sequence $\{y_n\} \in X$ such that $ABx_n = Jy_n$. Hence,

$$\lim_{n \to \infty} ABx_n = \lim_{n \to \infty} Jy_n = u \qquad \dots (17)$$

From condition (13), we have

$$\int_{0}^{d(ABx_{n},STy_{n})} \phi(t)dt \leq k \int_{0}^{M(x_{n},y_{n})} \phi(t)dt \qquad \dots (18)$$

where,

 $M(x_n, y_n) = max \{ d(Ix_n, Jy_n), d(Ix_n, ABx_n), d(Jy_n, STy_n), d(Ix_n, STy_n), d(Jy_n, ABx_n) \}$

Taking limit as $n \to \infty$, we get

$$\lim_{n \to \infty} \int_0^{d(ABx_n, NTy_n)} \phi(t) dt \le k \lim_{n \to \infty} \int_0^{M(x_n, y_n)} \phi(t) dt \qquad \dots (19)$$

Since

$$\lim_{n \to \infty} d(Ix_n, Jy_n) = \lim_{n \to \infty} d(Ix_n, ABx_n) = \lim_{n \to \infty} d(Jy_n, ABx_n) = 0$$
$$\lim_{n \to \infty} d(STy_n, Jy_n) = \lim_{n \to \infty} d(Ix_n, STy_n) = \lim_{n \to \infty} d(STy_n, u)$$

Therefore, we have

$$\lim_{n \to \infty} \int_0^{d(u,sTy_n)} \phi(t) dt \le k \lim_{n \to \infty} \int_0^{d(u,sTy_n)} \phi(t) dt, \qquad \dots (20)$$

which is a contradiction, since $k \in [0, \frac{1}{2}]$. Hence $\lim_{n \to \infty} STy_n = u$. Since $ST(X) \subseteq I(X)$, so there exists a sequence $x_n \in X$ such that $STx_n = Ix_n$. Hence, we have

$$\lim_{n \to \infty} ABx_n = \lim_{n \to \infty} Jy_n = \lim_{n \to \infty} STy_n = \lim_{n \to \infty} Ix_n = u$$

Assume I(X) is closed, then there exists $v \in X$ such that Iv = u. We claim that ABv = u. Now from condition (13)

$$\int_{0}^{d(ABv,STy_{n})} \phi(t) dt \leq k \int_{0}^{M(v,y_{n})} \phi(t) dt \qquad \dots (21)$$

where

$$M(v, y_n) = \max\{d(Jy_n, ABv), d(Iv, Jy_n), d(Iv, ABv), d(STy_n, Jy_n), d(Iv, STy_n)\} \dots (22)$$

Since
$$\lim_{n \to \infty} d(Jy_n, ABv) = d(u, ABv)$$
$$\lim_{n \to \infty} d(Iv, Iv_n) = \lim_{n \to \infty} d(Iv, STv_n) = 0$$

$$\underset{n \to \infty}{\lim \alpha(r) (f(r))} = \underset{n \to \infty}{\lim \alpha(r) (f(r))} = \underset{n \to \infty}{\lim \alpha(r) (f(r))}$$

So, taking limit as $n \to \infty$ in (22), we conclude that

$$\int_0^{d(ABv,\omega)} \varphi(t) dt \le k \int_0^{d(u,ABv)} \varphi(t) dt \qquad \dots (23)$$

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which is a contradiction, since $k \in [0, \frac{1}{2}]$. Hence, $d(ABv, u) = 0 \Rightarrow ABv = u$. Now, we have ABv = u = Iv...(24) This proves that v is the coincidence point of (AB, I). Again $AB(X) \subseteq J(X)$ so there exists $w \in X$ such that ABv = Jw = uNow, we claim that STw = u. From condition (13), we have $\int_{0}^{d(u,STw)} \phi(t) dt = \int_{0}^{d(ABv,STw)} \phi(t) dt \le k \int_{0}^{M(v,w)} \phi(t) dt$ where $M(v,w) = \max\{d(Iv, Jw), d(Iv, ABv), d(Jw, STw), d(Iv, STw), d(Jw, ABv)\}$ $= \max \{ d(u, u), d(u, u), d(u, STw), d(u, STw), d(u, u) \}$ $= \max\{\hat{d}(u, u), d(u, STw)\}$ Hence $\int_0^{d(u, STw)} \phi(t)dt \le k \int_0^{\max\{d(u, u), d(u, STw)\}} \phi(t)dt$, Since $d(u, u) \leq 2d(u, STw)$ So if $max\{d(u, u), d(Bw, u)\} = d(u, u)$ or d(STw, u) we get the contradiction, since $\int_{0}^{d(u,STw)} \phi(t)dt \le 2k \int_{0}^{d(u,STw)} \phi(t)dt$ or $\int_{0}^{d(u,STw)} \phi(t)dt \le k \int_{0}^{d(u,STw)} \phi(t)dt \text{ and } k \in \left[0, \frac{1}{2}\right].$ We have, $d(u, STw) = 0 \Rightarrow STw = u$. Therefore, STw = u = Jw. This represents that w is the coincidence point of the maps ST and I. Hence, u = STw = Jw = Iv = ABvSince the pair (ST, J) and (AB, I) are weakly compatible so, STJw = JSTw, IABv = ABIvSince Iu = IABv = ABIv = ABu and Ju = JSTw = STJw = STu, we claim that STu = u. From condition (13), we have $\int_{0}^{d(u,sTu)} \phi(t) dt = \int_{0}^{d(ABv,sTu)} \phi(t) dt \le k \int_{0}^{M(v,u)} \phi(t) dt, \text{ where}$ $M(v,u) = \max\{d(Iv, Ju), d(Iv, ABv), d(Ju, STu), d(Iv, STu), d(Ju, ABv)\}$ $= \max\{d(u, STu), d(u, u), d(STu, STu), d(u, STu), d(STu, u)\}$ $= \max\{d(u, STu), d(u, u), d(STu, STu)\}$ Hence $\int_0^{d(u,STu)} \phi(t) dt \le k \int_0^{\max\{d(u,STu), d(u,u), d(STu, STu)\}} \phi(t) dt$ Since $d(u, u) \leq 2d(u, STu)$ and $d(STu, STu) \leq 2d(u, STu)$ So if $max\{d(u, STu), d(u, u), d(STu, STu)\} = d(u, STu), d(STu, STu)$ or d(u, u), we get the contradiction, since $\int_0^{d(u,sTu)} \phi(t) dt \le 2k \int_0^{d(u,sTu)} \phi(t) dt$ $\int_0^{d(u,sTu)} \phi(t) dt \le k \int_0^{d(u,sTu)} \phi(t) dt \text{ and } k \in \left[0, \frac{1}{2}\right).$ or We have, $d(u, STu) = 0 \Rightarrow STu = u$. Therefore, u = STu = Ju. Similarly, ABu = u = Iu. Hence, u = ABu = STu = Iu = Ju. This represents that *u* is a common fixed point of the mappings *AB*, *ST*, *I* and *J*. **Uniqueness:** If possible, let $z \neq u$ be other common fixed point of the mappings, then by the condition (13) $\int_{0}^{d(u,z)} \phi(t) dt = \int_{0}^{d(Au,Bz)} \phi(t) dt \leq k \int_{0}^{M(u,z)} \phi(t) dt$, where $M(u, z) = max\{d(Iu, Jz), d(Iu, ABu), d(Jz, STz), d(Iu, STz), d(Jz, ABu)\}$ $= \max \{d(u, z), d(u, u), d(z, z), d(u, z), d(z, u)\}$ $= max\{d(u, z), d(u, u), d(z, z)\}$ Hence $\int_{0}^{d(u,z)} \phi(t) dt \le k \int_{0}^{max\{d(u,z),d(u,u),d(z,z)\}} \phi(t) dt$

Since

 $\begin{aligned} &d(u,u) \leq 2d(u,z) \text{ and } d(z,z) \leq 2d(z,u) \\ &\text{So if } \max\{d(u,z), d(u,u), d(z,z)\} = d(u,z) \text{ or } d(u,u) \text{ or } d(z,z) \text{ we get the contradiction, since} \\ &\int_0^{d(u,z)} \phi(t) \, dt \leq 2k \int_0^{d(u,z)} \phi(t) \, dt \\ &\text{or } \quad \int_0^{d(u,z)} \phi(t) \, dt \leq k \int_0^{d(u,z)} \phi(t) \, dt \text{ and } k \in \left[0, \frac{1}{2}\right]. \end{aligned}$

We have, $d(u, z) = 0 \Rightarrow u = z$.

This establishes the uniqueness of the common fixed point of mappings *AB*, *ST*, *I* and *J*. Finally, we prove that *u* is also a common fixed point of A, B, S, T, I and J.

Let both the pairs (AB, I) and (ST, J) have a unique common fixed point u.

Then,

 $\begin{array}{l} Au = A(ABu) = A(BAu) = AB(Au) \\ Az = A(Iu) = I(Au) \\ Bu = B(ABu) = B(A(Bu)) = BA(Bu) = AB(Bu) \\ Bu = B(Iu) = I(Bu) \end{array}$

which implies that (AB, I) has common fixed points which are Au and Bu. We get thereby Au = u = Bu = Iu = ABu.

Similarly, using the commutativity of (S, T), (S, J) and (T, J), Su = u = Tu = Ju = STu can be shown. Now, we need to show that Au = Su (Bu = Tu).

By using condition (13), we have

$$\begin{split} \int_{0}^{d(Au,Su)} \varphi(t) \, dt &= \int_{0}^{d(A(ABu),S(STu))} \varphi(t) \, dt = \int_{0}^{d(A(BAu),S(TSu))} \varphi(t) \, dt \\ &= \int_{0}^{d(AB(Au),ST(Su))} \varphi(t) \, dt \\ &\leq \int_{0}^{M(Au,Su)} \varphi(t) \, dt \\ \text{where} , M(Au,Su) &= \max \left\{ d(I(Au),J(Su)), d(I(Au),AB(Au)), \\ &\quad d(J(Su),ST(Su)), d(I(Au),ST(Su)), d(J(Su),AB(Au)) \right\} \\ &= \max \left\{ d(Au,Su), d(Au,Au), d(Su,Su), d(Au,Su), d(Su,Au) \right\} \\ &= \max \left\{ d(Au,Su), d(Au,Au), d(Su,Su) \right\} \end{split}$$

Hence, $\int_0^{d(Au,Su)} \varphi(t) dt \le k \int_0^{\max \{d(Au,Su), d(Au,Au), d(Su,Su)\}} \varphi(t) dt$, Since

 $d(Au, Au) \le 2d(Au, Su)$ and $d(Su, Su) \le 2d(Au, Su)$ So if max $\{d(Au, Su), d(Au, Au), d(Su, Su)\} = d(Au, Su)$ or d(Au, Au) or d(Su, Su) we get the contradiction, since

$$\int_0^{d(Au,Su)} \phi(t)dt \le 2k \int_0^{d(Au,Su)} \phi(t)dt$$

or
$$\int_0^{d(Au,Su)} \phi(t)dt \le k \int_0^{d(Au,Su)} \phi(t)dt \text{ and } k \in \left[0,\frac{1}{2}\right].$$

We have, $d(Au, Su) = 0 \Rightarrow Au = Su$. Similarly, Bu = Tu can be shown.

Consequently, *u* is a unique common fixed point of A, B, S, T, I and J.

If we put AB = A, ST = B in Theorem (3.2), we get the following, which generalize the result of Panthi and Kumari [20] in dislocated metric spaces.

Corollary 3.5. Let (X, d) be a complete dislocated metric space. Let $A, B, I, J: X \to X$ satisfying the following conditions

(i)
$$A(X) \subseteq J(X)$$
 and $B(X) \subseteq I(X)$

(ii)
$$\int_0^{d(Ax,By)} \phi(t) dt \le k \int_0^{M(x,y)} \phi(t) dt, k \in \left[0, \frac{1}{2}\right]$$

for all $(x, y) \in X \times X$ where $\emptyset: \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesgue integrable mapping which is summable, non-negative and such that

 $\int_0^{\epsilon} \phi(t) dt > 0 \text{ for all } \epsilon > 0.$ $M(x, y) = \max\{d(Ix, Jy), d(Ix, Ax), d(Jy, By), d(Ix, By), d(Jy, Ax)\}$ (iii) The pairs (A, I) or (B, J) satisfy E.A. property. (iv) The pairs (A, I) and (B, J) are weakly compatible.

If I(X) is closed then the mappings A,B,I and J have a unique common fixed point in X.

If we put A=B in the above Corollary 3.5, we can obtain the following corollary easily.

Corollary 3.6. Let (X, d) be a complete dislocated metric space. Let $A, I, J: X \to X$ satisfying the following conditions

(i) $A(X) \subseteq J(X)$ and $A(X) \subseteq I(X)$

(ii) $\int_0^{d(Ax,Ay)} \phi(t) dt \le k \int_0^{M(x,y)} \phi(t) dt, k \in \left[0, \frac{1}{2}\right)$

for all $(x, y) \in X \times X$ where $\emptyset: \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesgue integrable mapping which is summable, non-negative and such that

 $\int_0^{\epsilon} \phi(t) dt > 0 \text{ for all } \epsilon > 0.$ $M(x, y) = \max\{d(Ix, Jy), d(Ix, Ax), d(Jy, Ay), d(Ix, Ay), d(Jy, Ax)\}$ $(iii) \quad \text{The pairs } (A, I) \text{ or } (A, J) \text{ satisfy E.A. property.}$

(iv) The pairs (A, I) and (A, J) are weakly compatible.

If I(X) is closed then the mappings A,I and J have a unique common fixed point in X.

If we put I=J in the above Corollary 3.5, we can obtain the following corollaries easily.

Corollary 3.7. Let (X, d) be a complete dislocated metric space. Let $A, B, I: X \to X$ satisfying the following conditions

(i) $A(X) \subseteq I(X)$ and $B(X) \subseteq I(X)$

(ii) $\int_{0}^{d(Ax,By)} \phi(t)dt \leq k \int_{0}^{M(x,y)} \phi(t)dt, k \in \left[0, \frac{1}{2}\right]$

for all $(x, y) \in X \times X$ where $\emptyset: \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesgue integrable mapping which is summable, non-negative and such that

 $\int_0^{\epsilon} \phi(t) dt > 0 \text{ for all } \epsilon > 0.$ $M(x, y) = \max\{d(Ix, Iy), d(Ix, Ax), d(Iy, By), d(Ix, By), d(Iy, Ax)\}$

(iii) The pairs (A, I) or (B, I) satisfy E.A. property.

(iv) The pairs (A, I) and (B, I) are weakly compatible.

If I(X) is closed then the mappings A,B and I have a unique common fixed point in X.

If we putA=B and I=J in the above Corollary 3.5, we can obtain the following corollaries easily.

Corollary 3.8. Let (X, d) be a complete dislocated metric space. Let $A, I: X \to X$ satisfying the following conditions

(i) $A(X) \subseteq I(X)$

(ii) $\int_{0}^{d(Ax,Ay)} \phi(t) dt \leq k \int_{0}^{M(x,y)} \phi(t) dt, k \in \left[0, \frac{1}{n}\right]$

for all $(x, y) \in X \times X$ where $\emptyset: \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesgue integrable mapping which is summable, non-negative and such that

 $\int_0^{\epsilon} \phi(t) dt > 0 \text{ for all } \epsilon > 0.$ $M(x, y) = \max\{d(Ix, Iy), d(Ix, Ax), d(Iy, Ay), d(Ix, Ay), d(Iy, Ax)\}$ (iii) The pairs (A, I) satisfy E.A. property.

(iv) The pairs (A, I) are weakly compatible.

If I(X) is closed then the mappings A and I have a unique common fixed point in X.

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