MATLAB Simulation on Integration of Hybrid PV-Wind-Battery based system joined with Dc-Dc Converter

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ABSTRACT

The proposed paper has a control approach required for power run management of the system grid-connected hybrid PV-wind-battery based system with an efficient multi-input transformer joined bidirectional dc-dc converter is presented. The main aim of my project is to convince the load demand, manage the power flow from special sources, inject surplus power into the grid and charge the battery from grid as and when required. A transformer fixsed boost up half-bridge converter is used to exploit power from wind, while two directional buck-boost converters is used to exploit power from with battery charging/discharging control. A single-phase full-bridge bidirectional converter is used for feeding ac loads and communication with grid. The planned converter architecture has compressed number of power conversion stages with less component count, and reduced losses compared to offered grid-connected hybrid systems. Simulation results obtained using MATLAB/Simulink show the performance of the proposed control strategy.

Keywords: Multi-Input Converter (MIC), MPPT, hybrid system, solar photovoltaic.

INTRODUCTION

Fast consumption of fossil fuel holds, results in expanding vitality request and concerns over environmental change persuade control powergeneration from renewable energy sources. Sunlight based photovoltaic (PV) and wind have risen as well known vitality sources due to their eco-friendly nature and cost adequacy. Nonetheless, these sources are irregular in nature. Consequently, it is a test to supply steady and consistent power utilizing thesesources. This can be tended to by proficientlycoordinating with energy storage components.

The interesting correlative conduct of sun powered insulation and wind speed pattern combined has led to the exploration on their combination bringing about the hybrid PV-wind frameworks. For accomplishing the reconciliation of numerous renewable sources, the customary approach includes utilizing devoted single-input converters one for each source, which are associated with a typical dc-link. Bethat as it may, these converters are not successfully used, because of the discontinuous way of the renewable sources. Moreover, there are numerous power transformation stages which decrease the proficiency of the framework.

Hybrid PV-wind based system of power and their interfaces with the power network are the imperative research territories. Proposed multi-input half breed PV-wind control generation framework which has a buck/buck-help combined multi-input dc-dcconverter and a full-connect ac inverter. This system is essentially centered around enhancing the dc- interface voltage direction.

The utilization of multi-input converter (MIC) for cross breed control frameworks is pulling in expanding consideration on account of decreased part number, upgraded control thickness, smallness and concentrated control. Because of these favorable conditions, numerous topologies are proposed and they can be characterized into three gatherings, non- detached, completely segregated and halfway disengaged multi-port topologies.

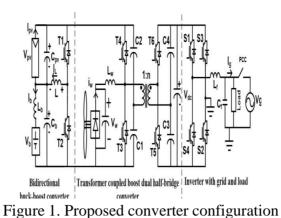
All the state of the art on converter topologies presented so far can oblige just a single renewable source and one energy storage element. Though, the proposed topology is fit for interfacing two renewable sources and a energy storage element. Consequently, it is more solid as two distinct sorts of renewable sources like PV and wind are utilized either separately or at the same time without increment in the segment tally contrasted with the existing state edge topologies.

The proposed framework has two renewable power sources, load, lattice and battery. Subsequently, a power flow management system is basic to adjust the power flow among every one of these sources. The primary goals of this framework are as per the following:

- ✓ To investigate a multi-object control scheme foroptimal charging of the battery utilizing numerous sources.
- ✓ Supplying un-interruptible energy to loads.
- ✓ Ensuring departure of surplus power from renewable sources to the network, and charging the battery from framework as and when required.

The network associated half breed PV-wind-battery based framework for family unit applications which can work either in remain solitary or grid associated mode. This framework is reasonable for family unit applications, where an ease, basic and reduced topology equipped for independent operation is attractive. The center of the proposed framework is the multi input transformer coupled bidirectional dc- dc converter that interconnects different power sources and the capacity component.

PROPOSED CONVERTER CONFIGURATION



The proposed converter comprises of a transformer coupled boost double half-bridge bidirectional converter fused with bidirectional buck-boost converter and a solitary stage full-connect inverter. The proposed converter has decreased number of power transformation stages with less part check and high productivity contrasted with the existing grid associated plans. The topology is straightforward and needs just six power switches. The schematic graph of the converter is delineated in Fig.1. The boost double half-bridge converter has two dc-interfaces on both sides of the high recurrence transformer. Controlling the voltage of one of the dc-link, guarantees controlling the voltage of the other. This makes the control procedure basic. Besides, extra converters can be incorporated with any of the two dc-joins. A bidirectional buck-help dc-dc converter is associated with the essential side dc-connection and single-stage full scaffold bidirectional converter is associated with the dc-connection of the auxiliary side.

The contribution of the half-bridge converter is designed by associating the PV exhibit in arrangement with the battery, accordingly incorporating an inherent boosting stage for the scheme. The boosting capacity is further improved by a high frequency step-up transformer. The transformer likewise guarantees galvanic segregation to the heap from the sources and the battery.

Bidirectional buck help converter is utilized to bridle control from PV alongside battery charging/releasing control. The one of a kind element of this converter is that MPP following, battery charge control and voltage boosting are refined through a solitary converter.

Transformer coupled boost half-bridge converter isutilized for harnessing power from wind and a solitary stage full-connect bidirectional converter is utilized for sustaining air conditioning burdens and association with framework. The proposed converter has diminished number of force change stages with less segment tally and high proficiency contrasted with the current network associated converters.

The power flow of wind source is controlled through a unidirectional boost half-bridge converter. For acquiring MPP successfully, smooth variety in source current is required which can be gotten utilizing an inductor.

In the proposed topology, an inductor is put in arrangement with the wind source which guarantees constant current and accordingly this inductor current can be utilized for keeping up MPP current.

During the ON time of T 3, the primary voltage VP =-VC1. The secondary voltage VS = nVp = -nVC1 =-VC3, or VC3 = nVC1 and voltage across primary inductor Lw is Vw. When T 3 is turned OFF and T 4 turned ON, the primary voltage VP = VC2. Secondary voltage VS = nVp = nVC2 = VC4 and voltage across primary inductor Lw is Vw - (VC1 +VC2). It can be proved that

$$(\text{VC1} + \text{VC2}) = \frac{\text{Vw}}{(1 - \text{Dw})}$$

The capacitor voltages are considered constant in steady state and they settle at VC3 = nVC1, VC4 = nVC2. Hence the output voltage is given by

$$Vdc = VC3 + VC4 = n \frac{Vw}{(1 - Dw)} \dots (1)$$

In this manner, the yield voltage of the auxiliary side dc-connection is an element of the obligation cycle of the essential side converter and turns proportion of transformer.

In the proposed design as appeared in Fig. 2(a), abidirectional buck-support converter is utilized for MPP following of PV exhibit and battery charging/releasing control. Promote, this bidirectionalbuck-support converter charges/releases the capacitor bank C1-C2 of transformer coupled half-connect help converter in view of the heap request. The half- connect help converter extricates vitality from thetwist source to the capacitor bank C1-C2. Amid battery charging mode, when switch T 1 is ON, the vitality is put away in the inductor L. At the point when switch T 1 is killed and T 2 is turned ON, vitality put away in L is exchanged to the battery. On the off chance that the battery releasing current is more than the PV current, inductor current gets to bedistinctly negative.

Here, the stored energy in the inductor increases when T 2 is turned on and decreases when T 1 is

 $V_b = \frac{D}{D} V_{Pv}$. turned on. It can be proved that output voltage of the transformer Coupled boost half-bridge converter is given by

$$V_{dc} = n(V_{C1} + V_{C2}) = n(V_b + V_{PV}) = \frac{nV_W}{1 - D_W}$$
(2)

This voltage is n times of primary side dc-link voltage. The primary side dc-link voltage can be controlled by half-bridge boost converter or by bidirectional buck- boost converter. The relationship between the average value of inductor, PV and battery currentover a switching cycle is given by IL = Ib + Ipv. It is evident that, Ib and Ipv can be controlled by controlling IL. Therefore, the MPP operation is assured by controlling IL while maintaining proper battery charge level. IL is used as inner loop control parameter for faster dynamic response while for outerloop, capacitor voltage across PV source is used for ensuring MPP voltage. An incremental conductancemethod is used for MPPT.

A. Limitations and Design issues

The output voltage Vdc of transformer coupled boost dual half-bridge converter, depends on MPP voltage of PV array VPV mpp, the battery voltage Vb and the transformer turns ratio n.

PROPOSED CONTROL SCHEME FOR POWER FLOW MANAGEMENT

A lattice associated half and half PV-wind-battery based framework comprising of four power sources (grid, PV, wind source and battery) and three power sinks (network, battery and load), requires a control conspire for power flow management to adjust the power flow among these sources. The control reasoning for power flow management of the multi- source framework is produced in view of the power adjust standard. In the remain solitary case, PV and wind source produce their comparing MPP power and load takes the required power. For this situation, the power adjust is accomplished by charging the battery until it achieves its greatest charging current farthest point Ibmax. After achieving this farthest point, to guarantee control adjust, one of the sources or both need to go astray from their MPP control in view of the heap request. In the lattice associatedframework both the sources dependably work at their MPP. Without both the sources, the power is attracted from the lattice to charge the battery as and when required. The condition for the power management of the system is given by:

 $V_{Pv}I_{Pv} + V_{W}I_{W} = V_{b}I_{b} + V_{g}I_{g} \dots (3)$

The peak value of the output voltage for a single-phase full bridge inverter is,

 $\hat{V} = m_a V_{dc}$... (4) and the dc-link voltage is, $Vdc = n (V_{pv} + V_b)$... (5)

Hence, by substituting for Vdc in (4), gives,

 $V_{2g} = {}^{1} m_a n (V_{pv} + V_b) \dots (6)$

In the boost half-bridge converter,

 $V_{\rm w} = (1 - D_{\rm w})(V_{pv} + V_b) \dots (7)$

Now substituting Vw and Vg in (3), $V_{pv}I_{pv} + (V_{pv} + V_b)(1 - D_w)I_w = V_bI_b +$ ¹ $m_an(V_{pv} + V_b)I_g$... (8) After Simplification $I = I \int_{pv} \frac{(1 - D_{pv})}{D_{pv}} + I \int_{w} \frac{(1 - D_w)}{D_{pv}} - I \int_{w} \frac{(man)}{g \sqrt{2}D_{pv}}$... (9)

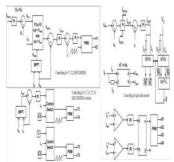


Figure 2. controlling for circuit shown in figure 1

from the above conditions it is obvious that, if there is an adjustment in power decreases from either PV or wind source, the battery current can be directed by controlling the lattice current Ig. Thus, the control of a solitary stage full-connect bidirectional converter relies on upon accessibility of network, power from PV and wind sources and battery charge status. Its control procedure is delineated utilizing Fig. 3. To guarantee the supply of continuous energy to basic burdens, need is given to charge the batteries. In the wake of achieving the most extreme battery charging current point of confinement Ibmax, the surplus power from renewable sources is bolstered to the grid. Without these sources, battery is charged from the framework.

Simulation results:

The steady state response of the system during the MPPT mode of operation is shown in Fig. 3. The values for source-1 (PV source) is set at 35.4 V (Vmpp) and 14.8 A (Impp), and for source-2 (wind source) is set at 37.5 V (Vmpp) and 8 A (Impp). It can be seen that Vpv and Ipv of source-1, and Vw and Iw of source-2 attain set values required for MPPoperation. The battery is charged with the constant magnitude of current and remaining power is fed to the grid.

The system response for step changes in the source-1 Insolation level while operating in MPPT mode is shown in Figure 5. Until 2 s, both the sources areoperating at MPPT and charging the battery with constant current and the remaining power is fed to the grid. At instant 2 s, the source-1 insolation level is increased. As a result the source-1 power increases

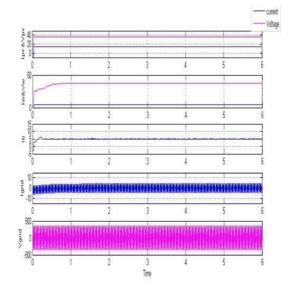


Figure 3. Ipv and Vpv, Iw and Vw, Ib, Igrid and Vgridwhen all PV and wind sources are active

and both the sources continue to operate at MPPT. Though the source-1 power has increased, the battery is still charged with the same magnitude of current and power balance is achieved by increasing the power supplied to the grid. At instant 4 s, insolation f source-1 is brought to the same level as before 2s. The power supplied by source-1 decreases. Batterycontinues to get charged at the same magnitude of current, and power injected into the grid decreases. The same results are obtained for step changes

in source-2 wind speed level

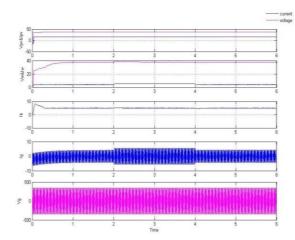


Figure 4. Ipv and Vpv, Iw and Vw, Ib, Igrid and VgridWhen wind sources increases

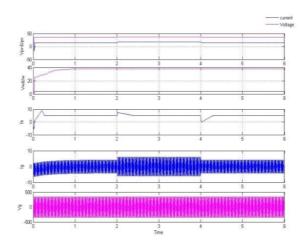


Figure 5. Ipv and Vpv, Iw and Vw, Ib, Igrid and VgridWhen PV sources increases

By connecting a multi level inverter we know the harmonics are going to decrease and that can be used in grid current and voltage. In this we are used a single phase diode clamped multilevel inverter on the grid side.

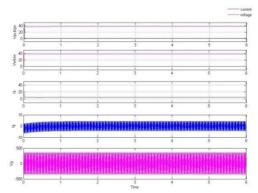


Figure 6. pv and Vpv, Iw and Vw, Ib, Igrid and VgridWhen both PV and wind sources are inactive

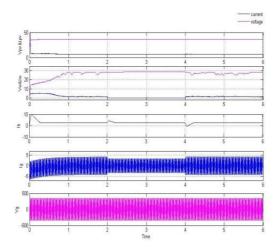


Figure 7. Ipv and Vpv, Iw and Vw, Ib, Igrid and VgridWhen wind sources reduces suddenly

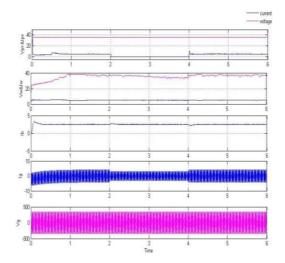


Figure 8. Ipv and Vpv, Iw and Vw, Ib, Igrid and VgridWhen PV sources decreases suddenly.

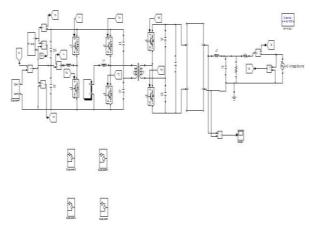
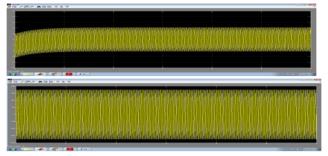


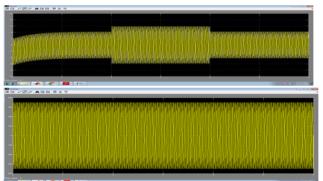
Figure 9. Simulation model for grid connected pvwind battery with multilevel inverter

Here different cases of above model performance wave forms of the project shown below and these consist of grid voltage and currents. On x axis time in sec and on y axis magnitudes of current and voltage

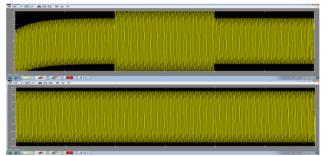




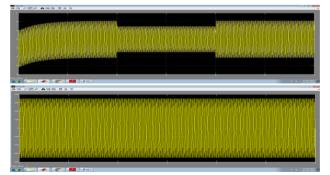
Case 2: PV increases



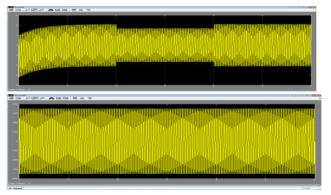
Case 3: wind increases



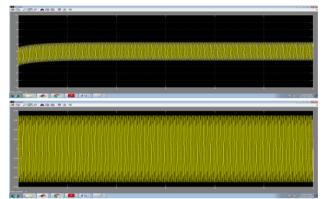
Case 4: PV inactive



Case 5: wind is inactive



Case 6: Both are inactive



Observe it in below table

	Ig	Vg
Base	0.81%	0.10%
Ext	0.08%	0.09%

CONCLUSION

The proposed cross system provides a well-dressed integration of PV and wind source to extract maximum energy from the all sources. It is realized by a novel multi-input transformer attached bidirectional dc-dc converter derived by aconventional full-bridge inverter. A flexible control strategy which achieves better utilization of PV, windpower, battery capacities without effecting life of battery and power flow management in a grid- connected hybrid PV-wind-battery based systemfeeding ac loads is presented. Detailed simulation studies are carried out to determine the viability of the scheme, by placing multilevel inverter I observed the improvement.

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